## Tilt Position Sensor Circuit

## CIRCUIT DESCRIPTION

The tilt position is sent to the ECU as a voltage signal from the position sensor. A constant 5 V is supplied to terminal 2 of sensor. The voltage at terminal 3 varies with position and is input to the ECU.
WIRING DIAGRAM


## INSPECTION PROCEDURE

1 Check voltage between terminals TIS and E1 of ECU connector.


## PREPARATION:

(a) Remove ECU with connectors still connected.
(b) Remove tilt position sensor with connector still connected.

## CHECK:

Measure voltage between terminals TIS and E1 of ECU connector, while turning the tilt position sensor lever slowly by hand from raised side to lowered side.
OK:

## Voltage:

Fully raised: Below 1 V
Fully lowered: 4-6 V
HINT:
As the lever is turned, the voltage should increase gradually without interruption.

## NG

$2 \square$
Check［tilt［position／sensor．

## PREPARATION：

Disconnect｜Zilt［position\＄ensor［Gonnector．


## CHECK：

 position／\＄ensor［Gonnector．
OK：
Resistance： 4 － $\mathbf{6 k}$ k

## CHECK：

Measure［the［resistanceПbetween【terminals［TIS［and［F1［bf［tilt position $\$$ ensor［\＄onnector，［while［turning［the＿tilt［position／\＄ensor lever\＄lowly［by［hand｜from［raised／\＄ide［tollowered\＄ide．
OK：

## Resistance：

Fully［raised：［Below 100＠
Fully［lowered：$\sqrt{4}$－ $\mathbf{6}^{6} \mathbf{k} \Omega$
HINT：
Asthe Tever［isturned，the resistance\＄hould Increase［gradually without［interruption．


## OK

$3 \square$ Check［harness［and／connectors［between［ECU［7nd［tilt［position／sensor （See■pageПN－30）．


Repair or replace harness or connector．


## Check and replace ECU．

